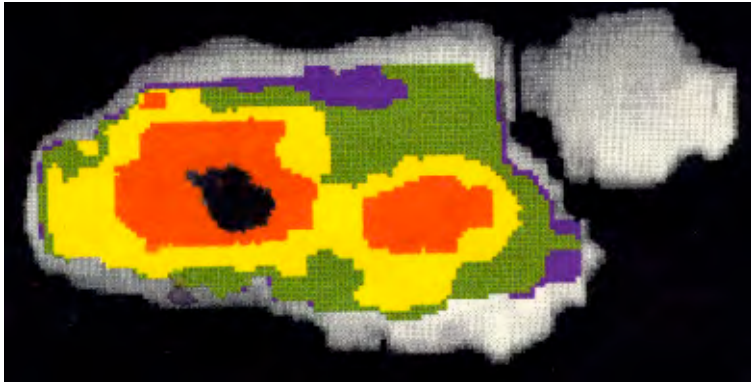


# Anatomy and mechanics of the wrist

G.R. Sennwald

**Consultant Handsurgeon**  
**Handsurgery Unit, University of Geneva**

26° Congresso Brasileiro  
De Cirurgia da Mão



# Anatomy and mechanics of the wrist

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*Anatomy and mechanics of the wrist*

➔ Teaching:

Anatomy ?

Mechanics ?

Both are basic?

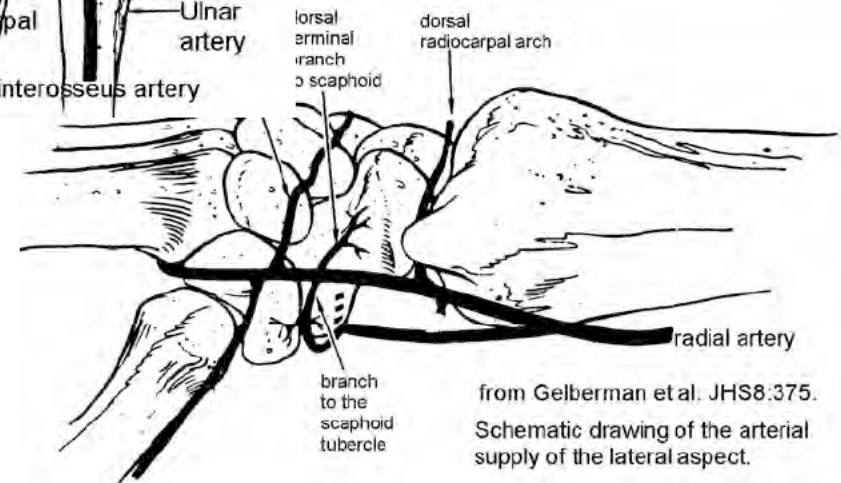
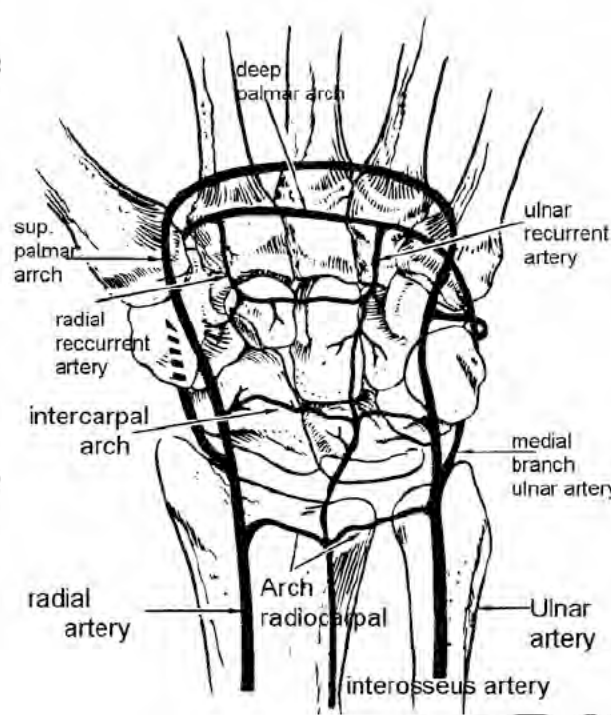
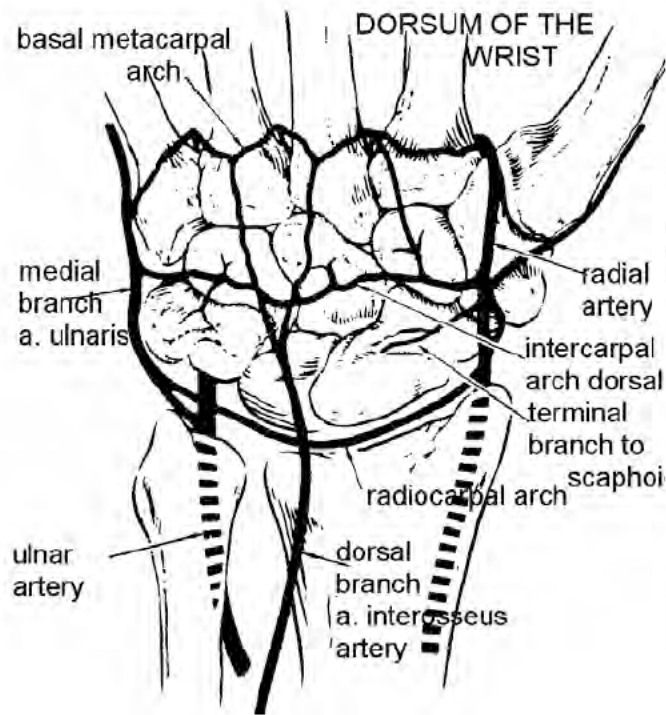
Both are evidence?

Both are related to one another!

*Anatomy and mechanics of the wrist*

# Anatomy

# Anatomy and mechanics of the wrist vessels



Seems accepted & important vascularisation of scaphoid lunate

from Gelberman et al. JHS8:375. Schematic drawing of the arterial supply of the lateral aspect.

## *Anatomy and mechanics of the wrist*

**Vascular pattern of the lunate accoring to Gelberman:  
3 major vascular pattern as presented:**



**30%**

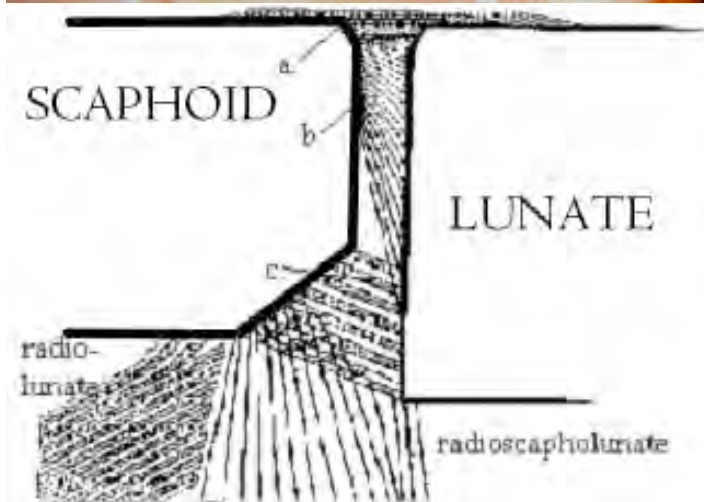
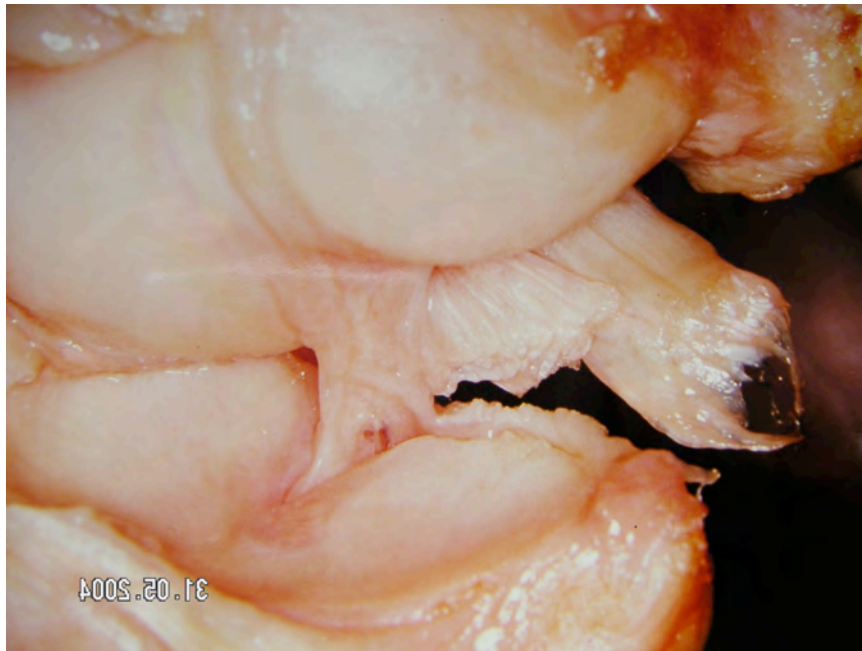
**10%**

**60%**

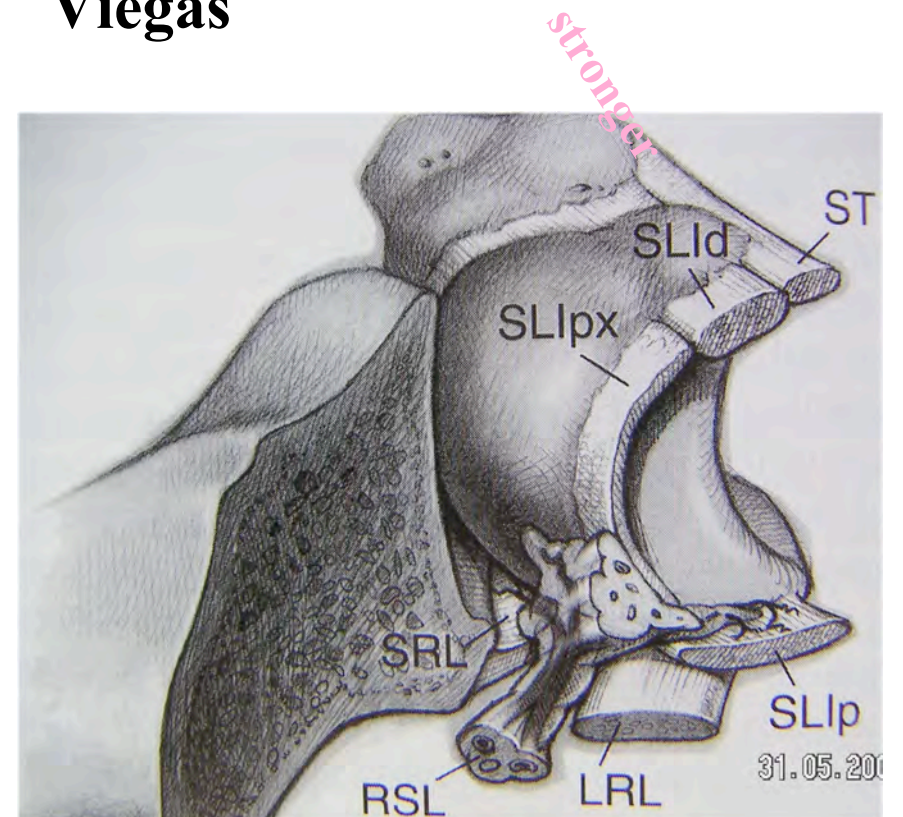
**But 20% have an exclusive palmar supply!**



# Anatomy and mechanics of the wrist



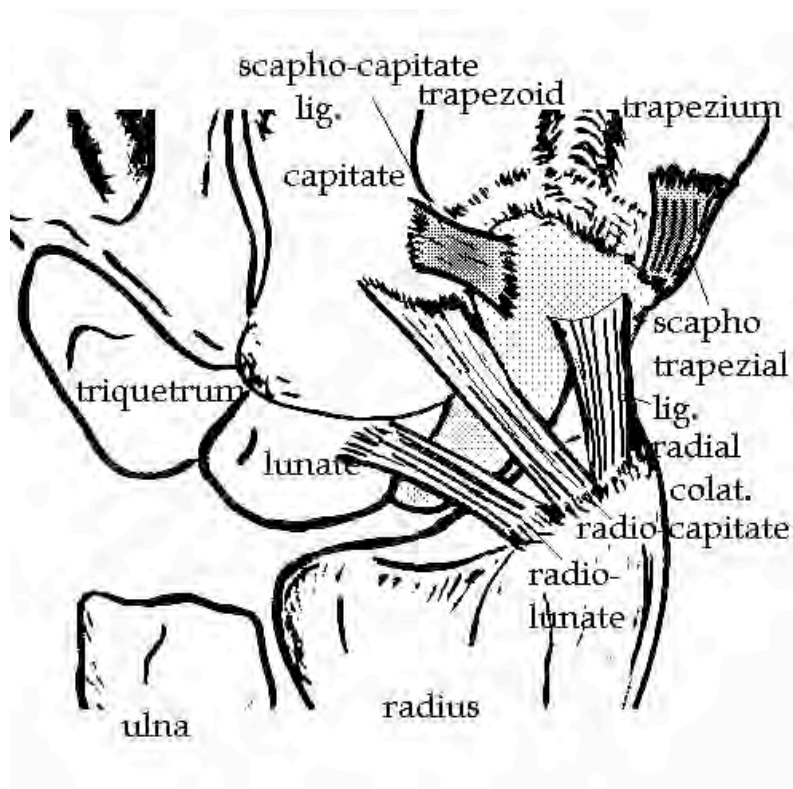
## Berger Viegas



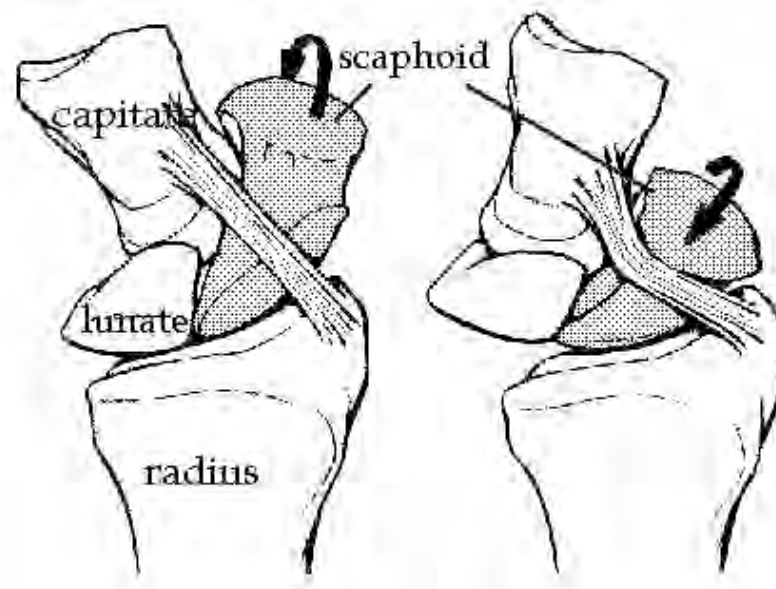


# *Anatomy and mechanics of the wrist*

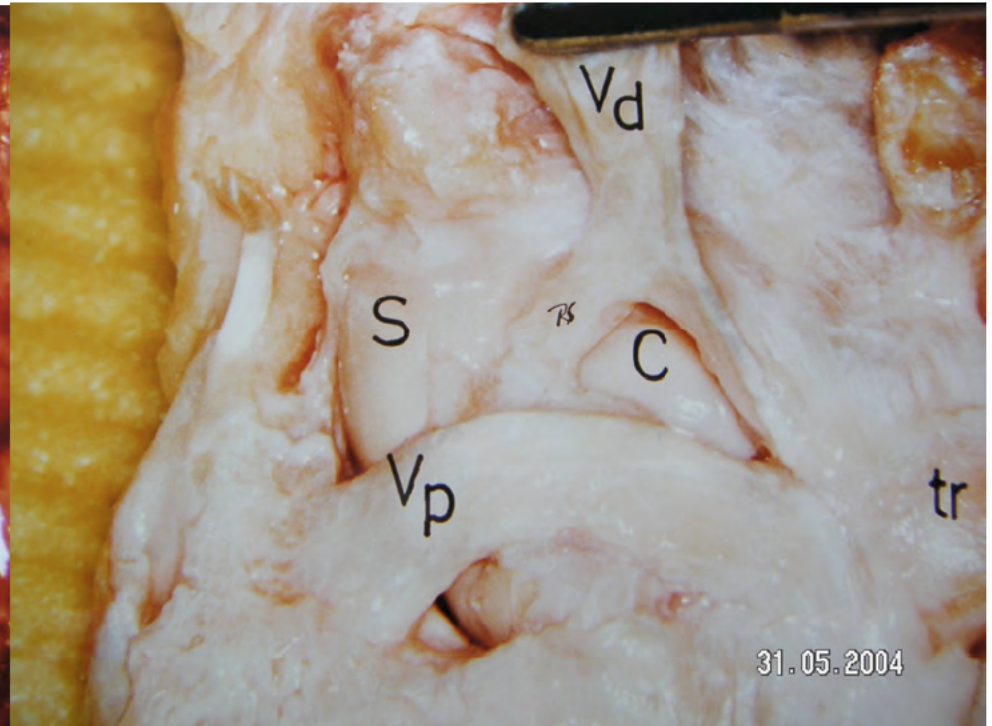
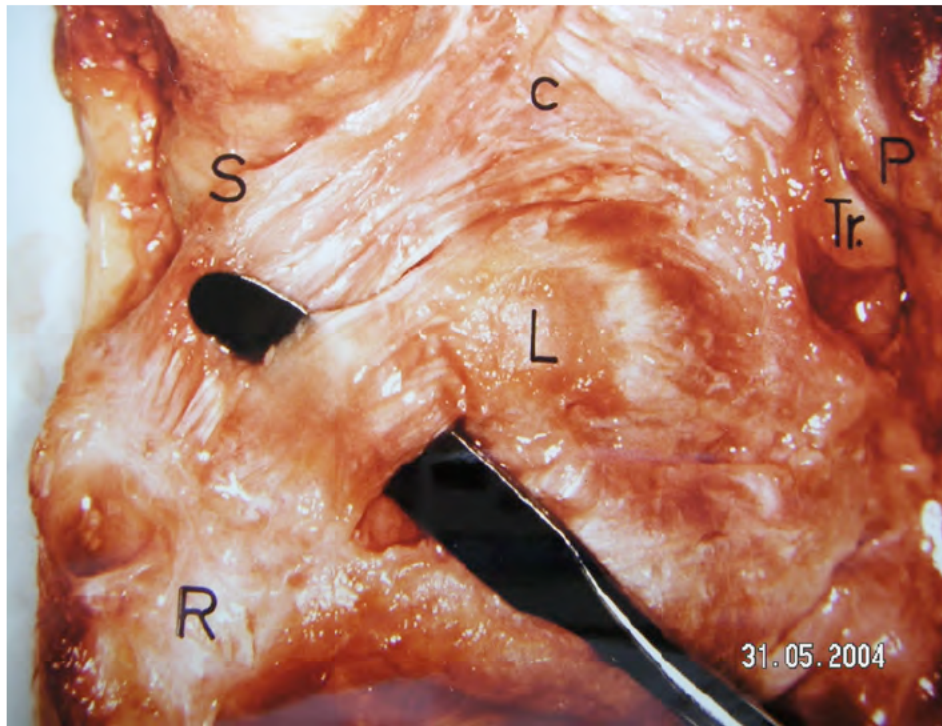
## **Ligaments** **Kuhlmann; Masquelet**



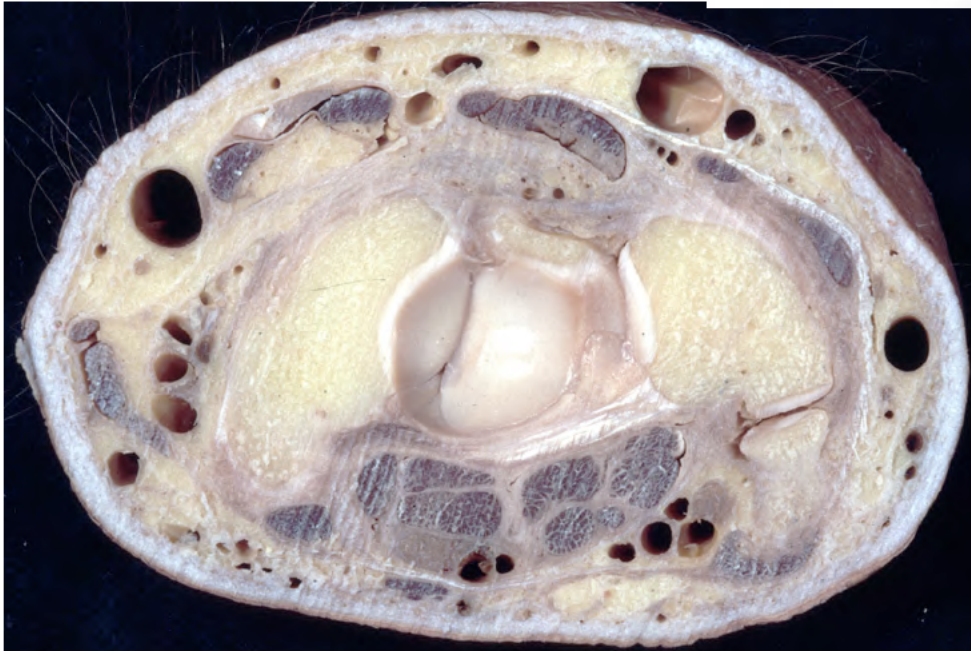
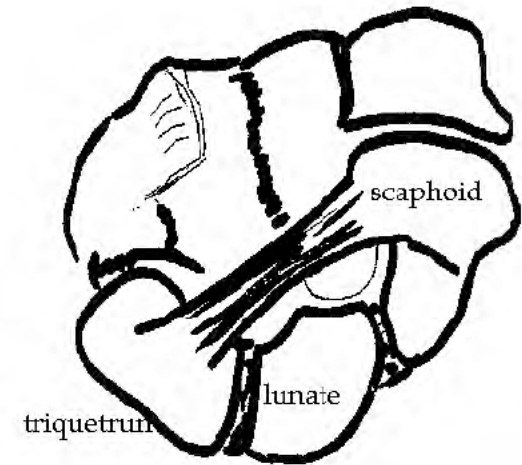
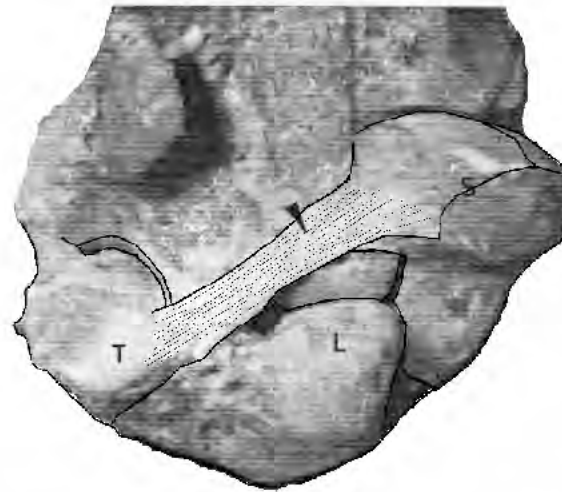
## **Verdan** **The RC ligament**



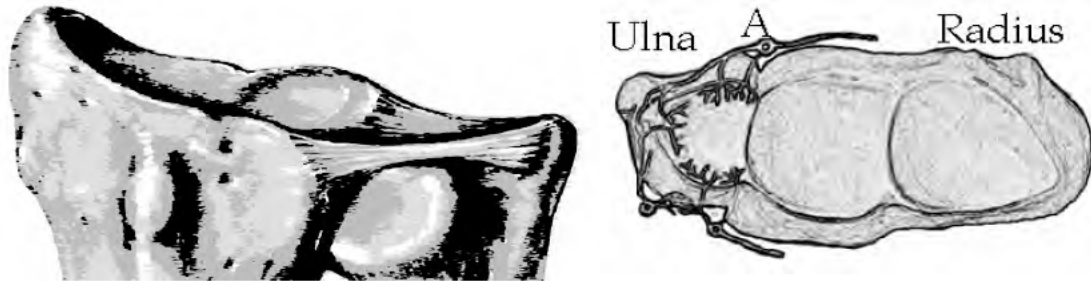
# *Anatomy and mechanics of the wrist*



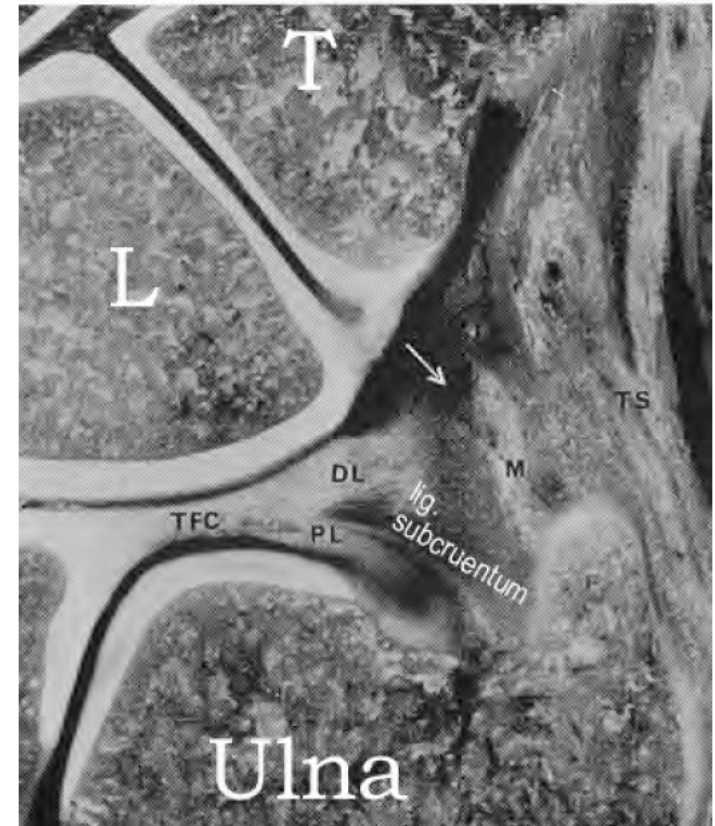
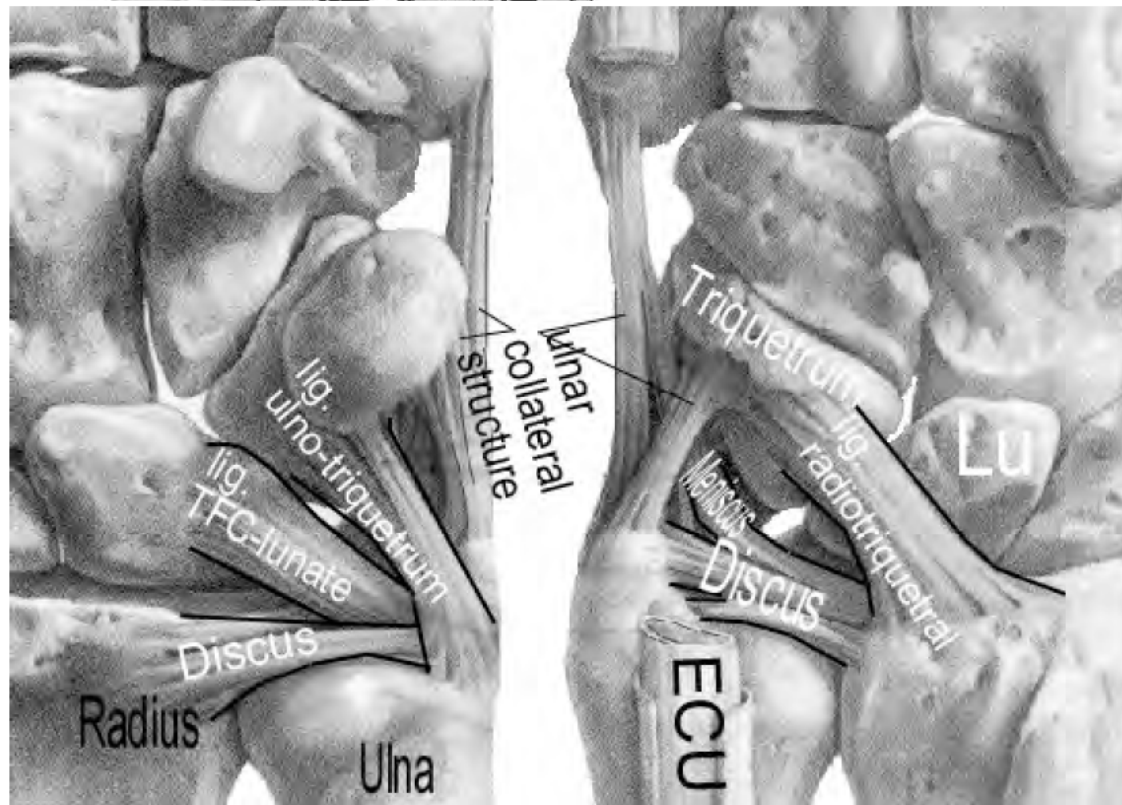
# *Anatomy and mechanics of the wrist*



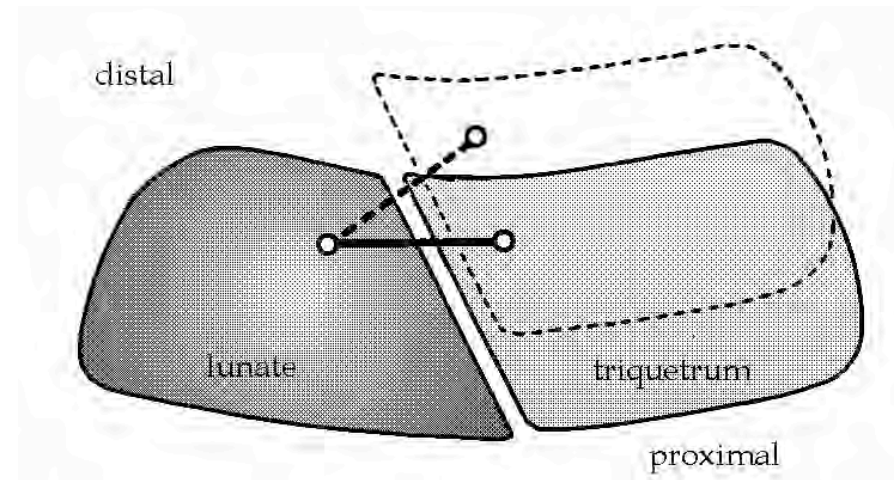
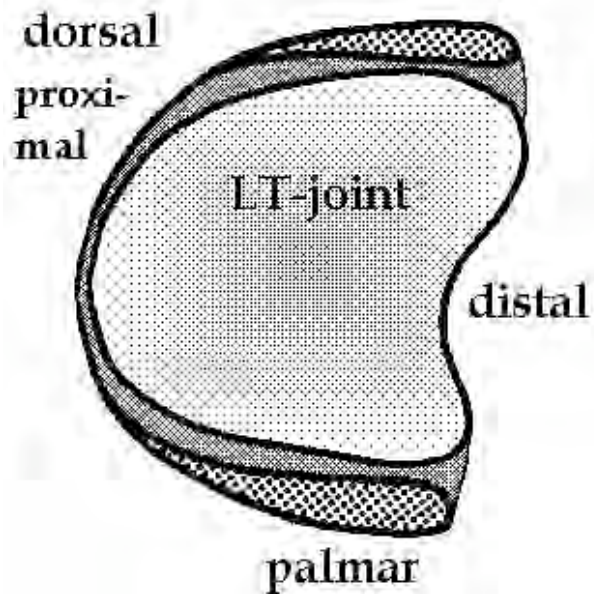
# Anatomy and mechanics of the wrist



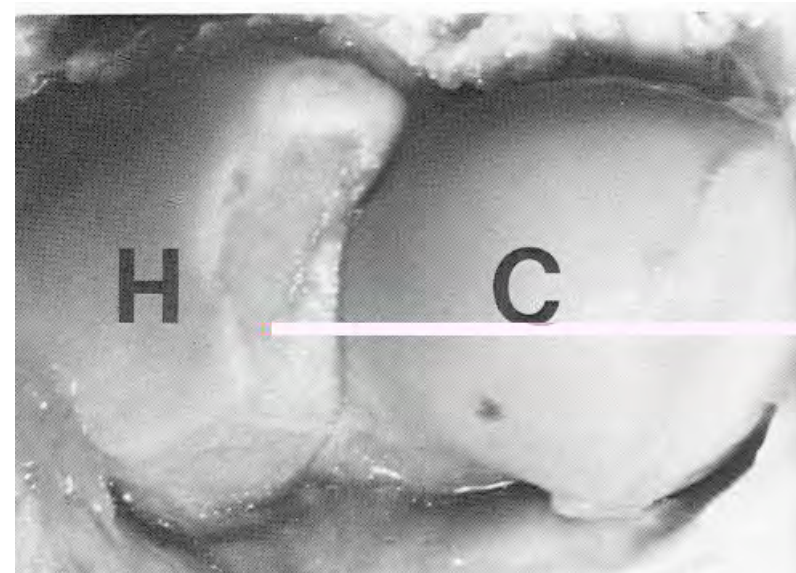
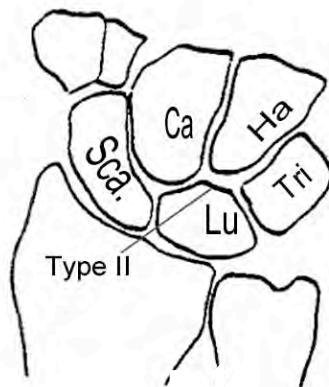
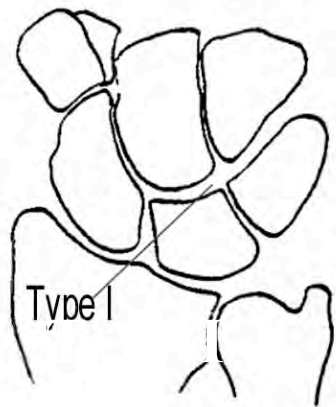
**Schmid**



# Anatomy and mechanics of the wrist

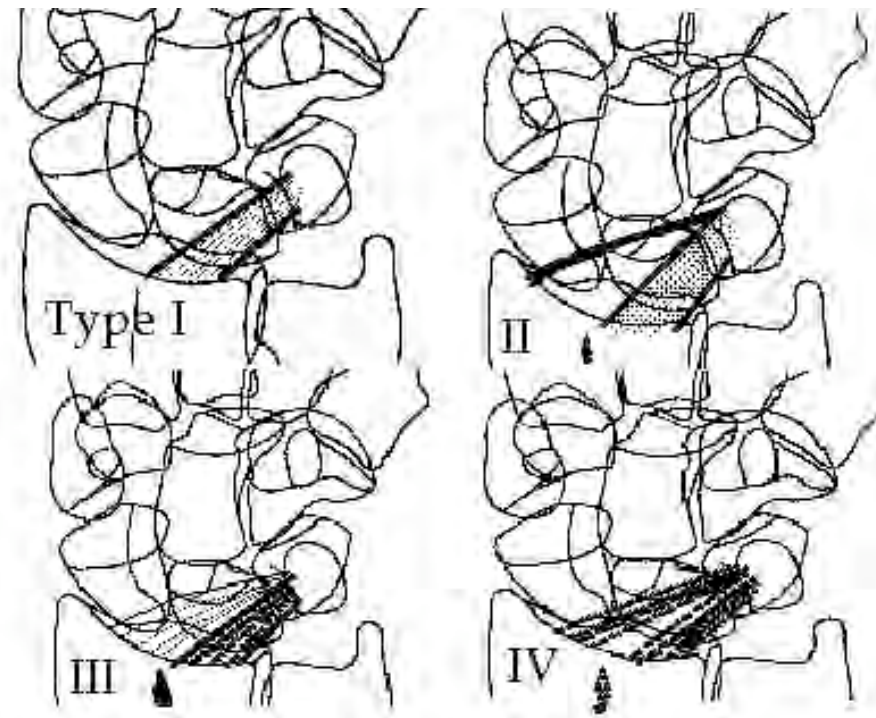
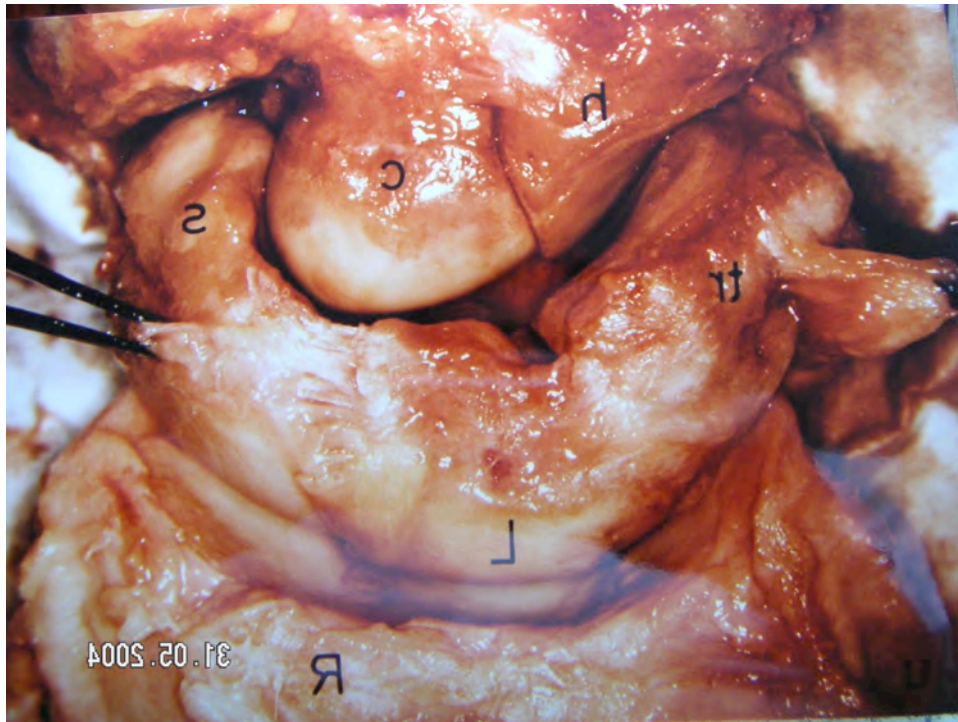


**inger**



# *Anatomy and mechanics of the wrist*

## **Viegas**



**Type I = 54 %**

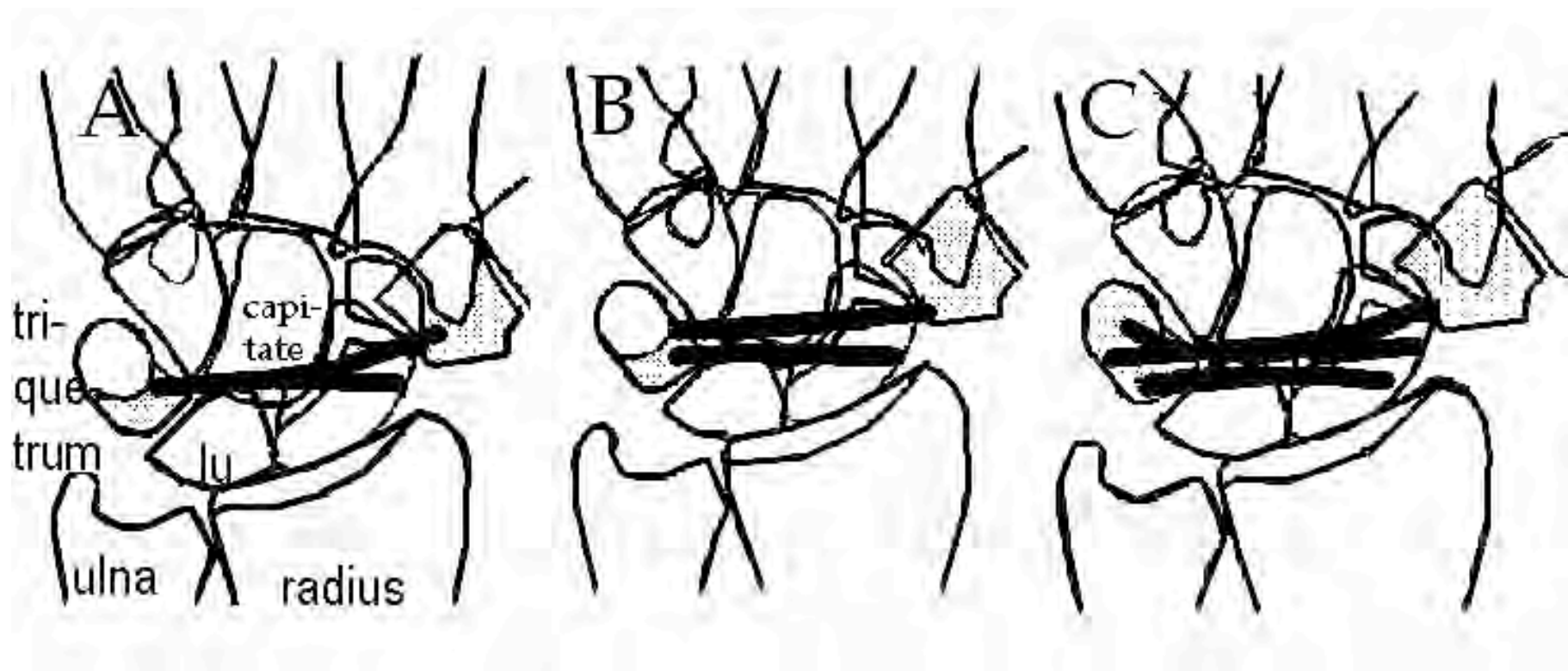
**III = 12%**

**II = 24%**

**IV = 9%**

*Anatomy and mechanics of the wrist*

*The DIC (viegas)*



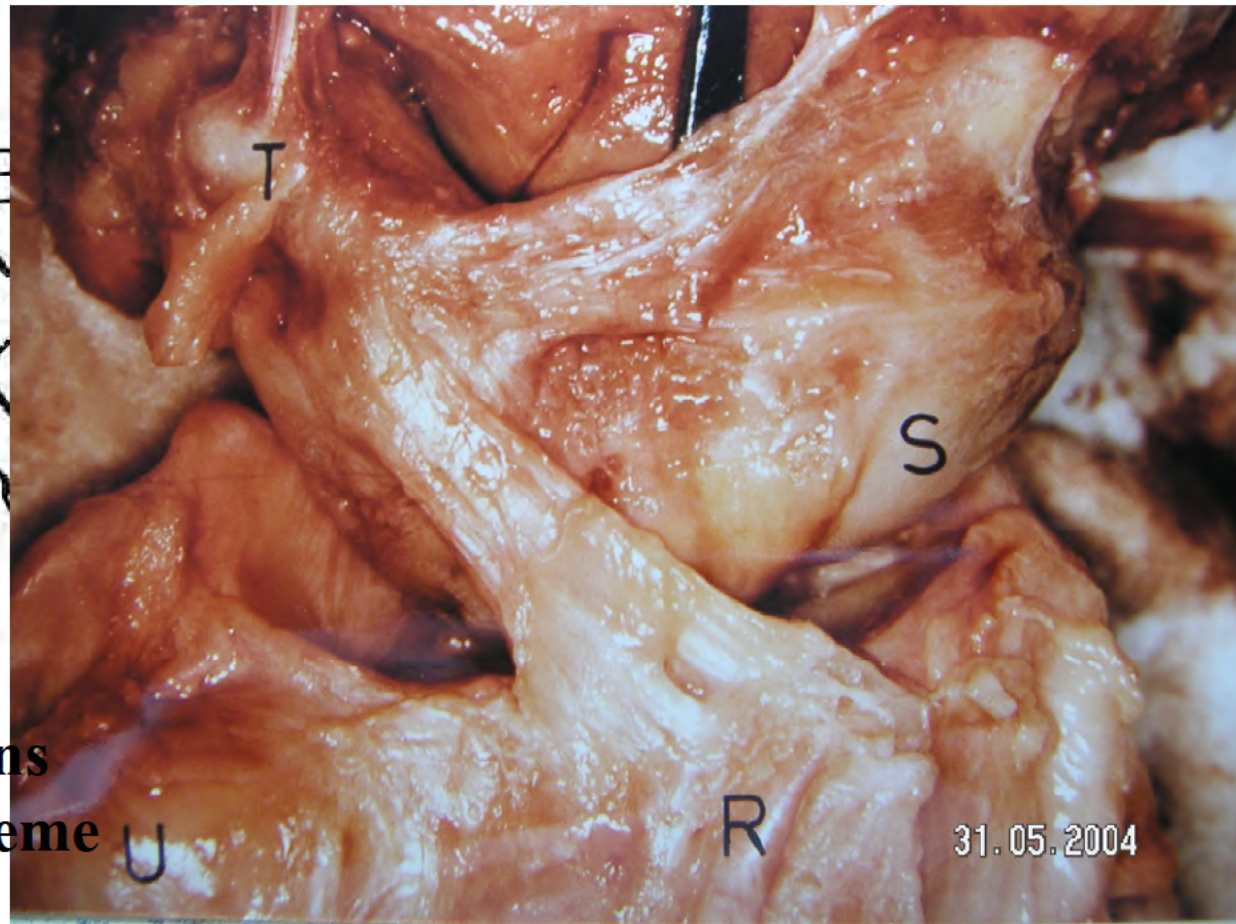
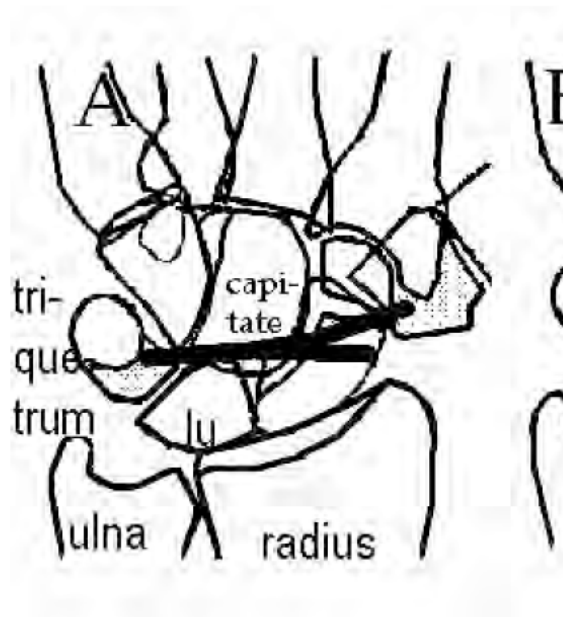
**30%**

**44%**

**26%**

# *Anatomy and mechanics of the wrist*

## **DIC, combined to dorsal SL**



**Various presentations**

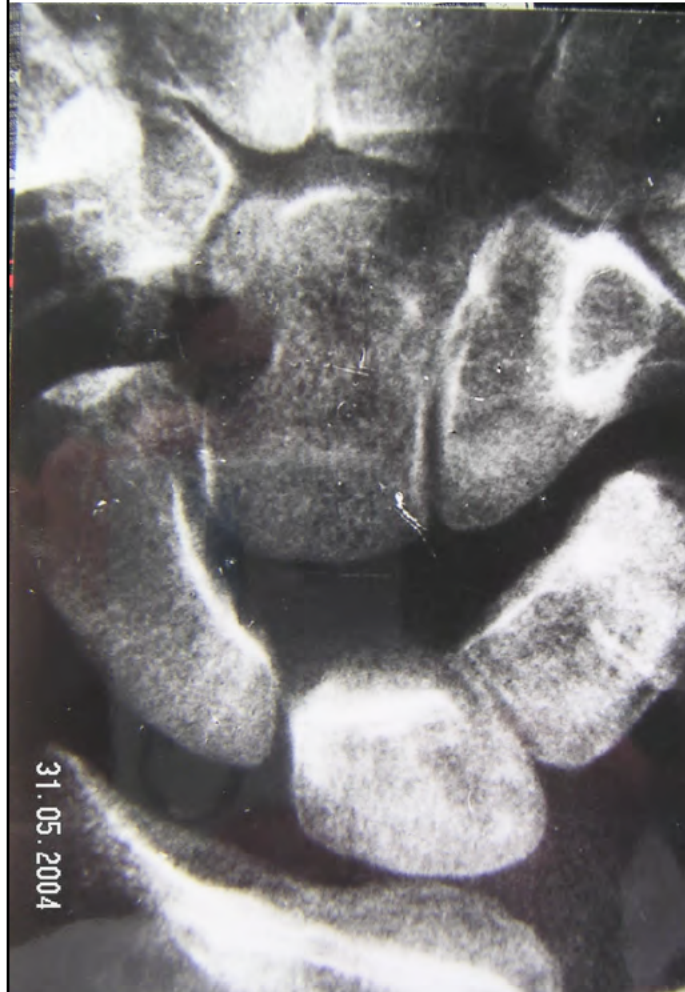
**Taleisnik: other scheme**

31.05.2004

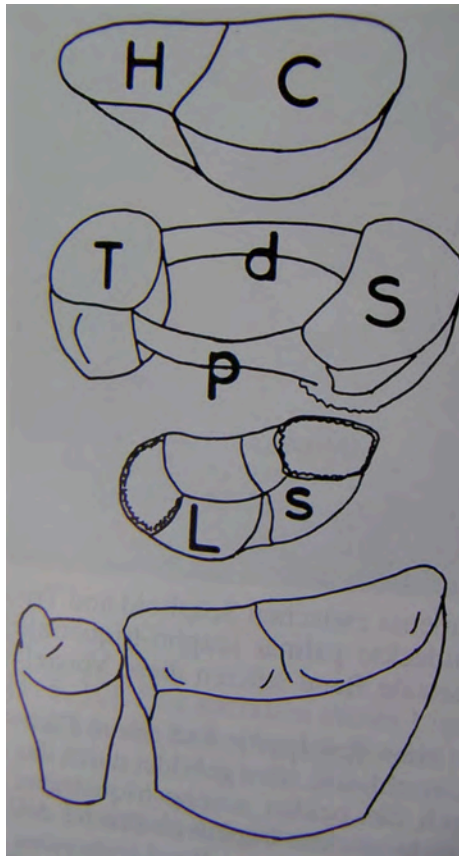


*Anatomy and mechanics of the wrist*

**Orientation of  
ligaments render  
ligamentotaxis  
inefficient**



# *Anatomy and mechanics of the wrist*



**Head of the  
capitate, fixed  
between  
dorsal &  
palmar ST  
ligament.**

**Potential shear  
forces =  
scaphoid  
fracture**



*Anatomy and mechanics of the wrist*

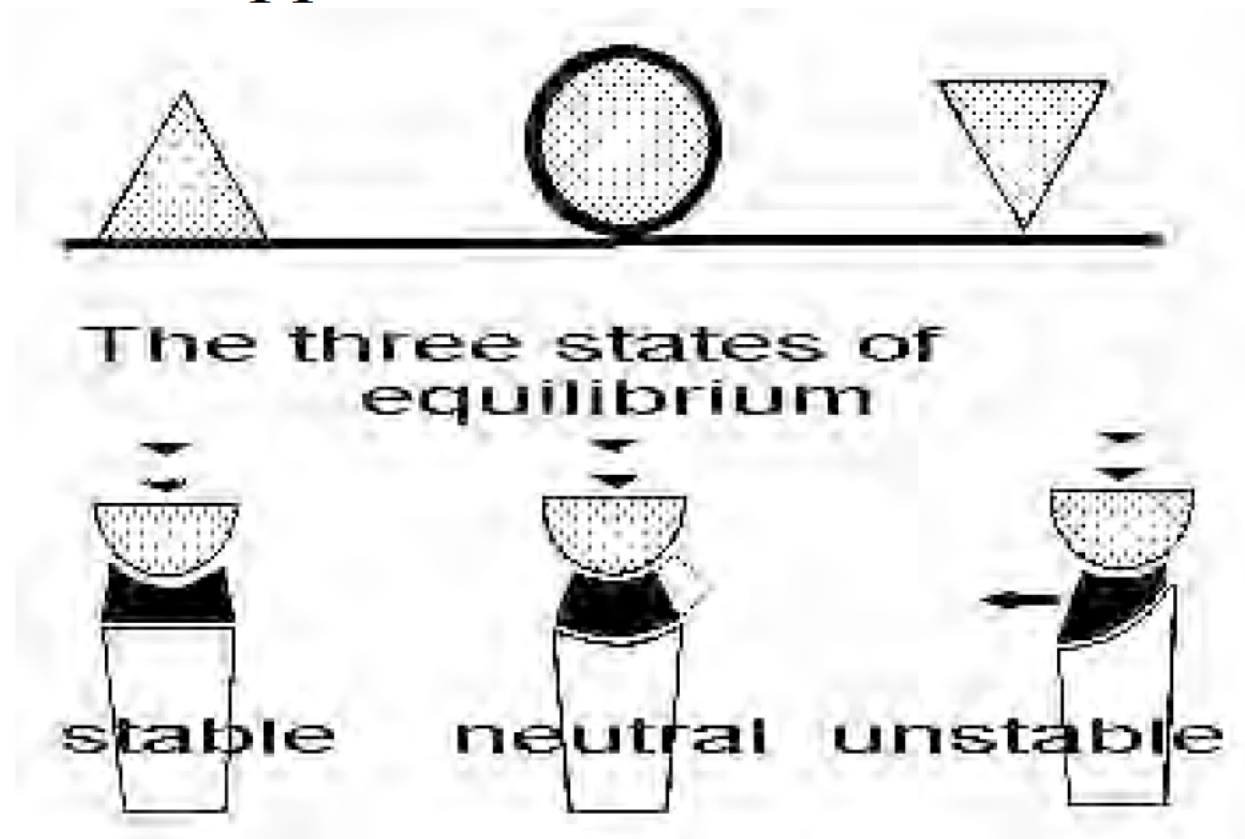
# Mechanics

Understanding of mechanical  
laws i.e.

load transfer  
stability.

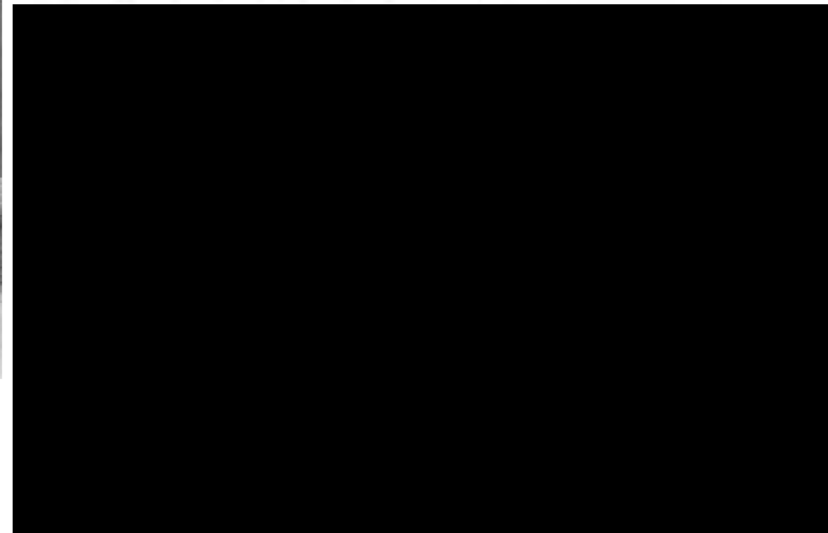
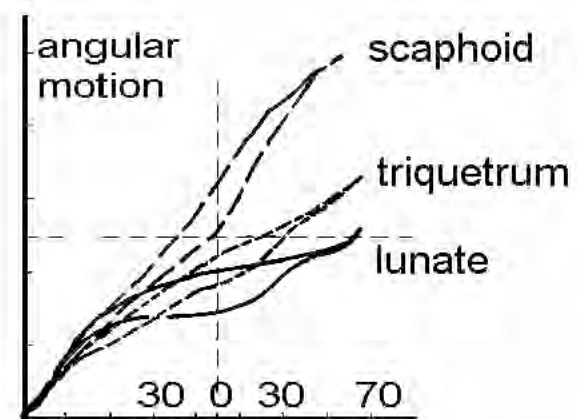
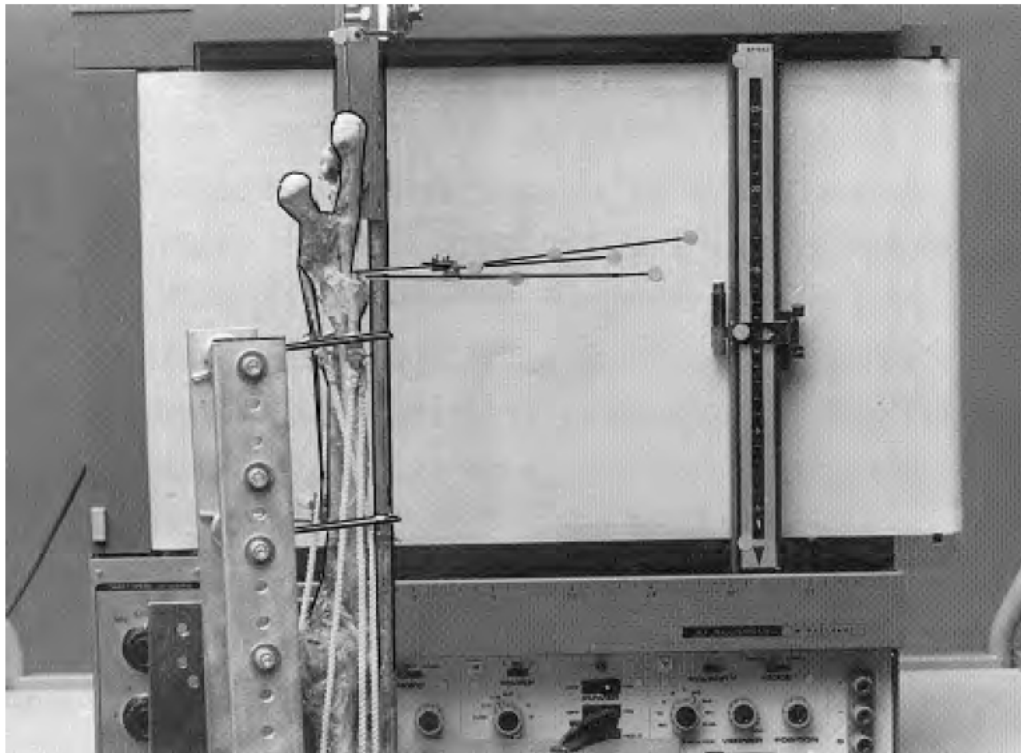
# *Anatomy and mechanics of the wrist*

Definition of stability  
Mechanical approach

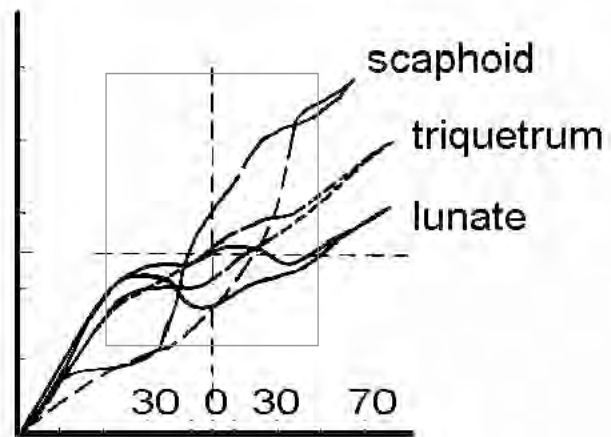
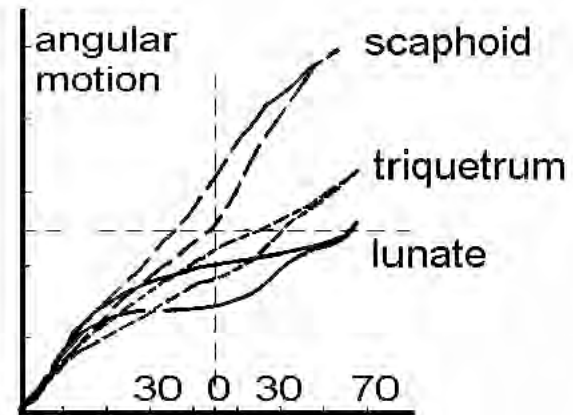
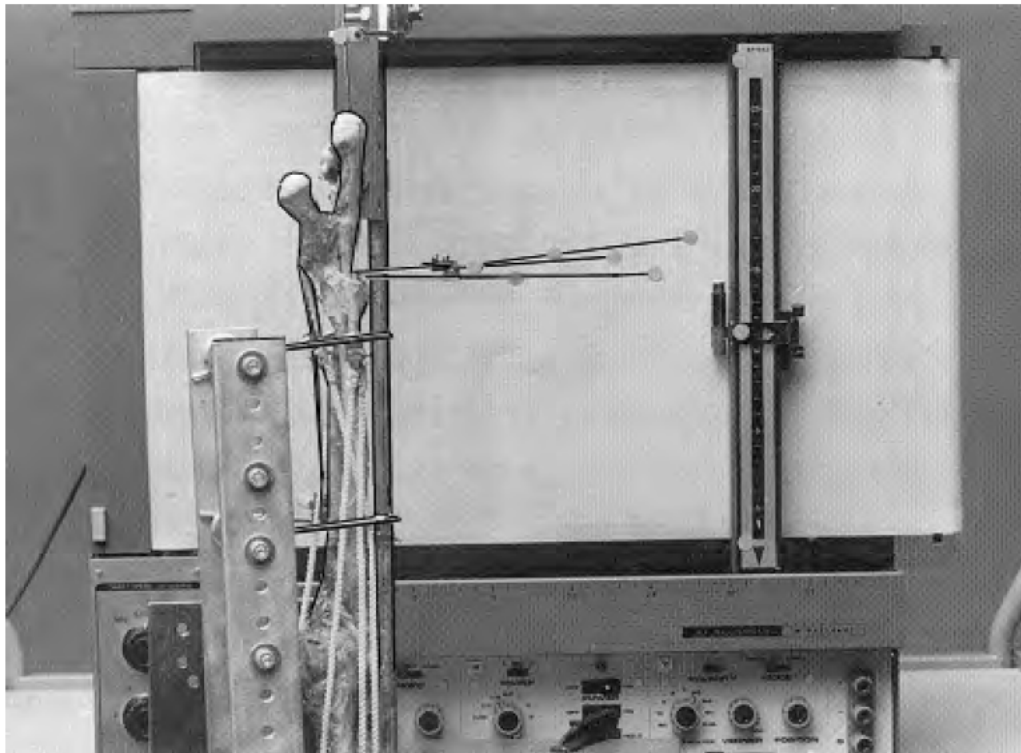


# *Anatomy and mechanics of the wrist*

All ligaments intact



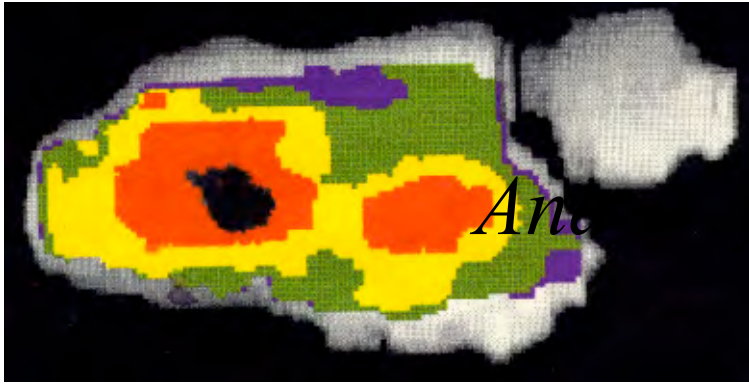
# *Anatomy and mechanics of the wrist*



ut

## *Anatomy and mechanics of the wrist*

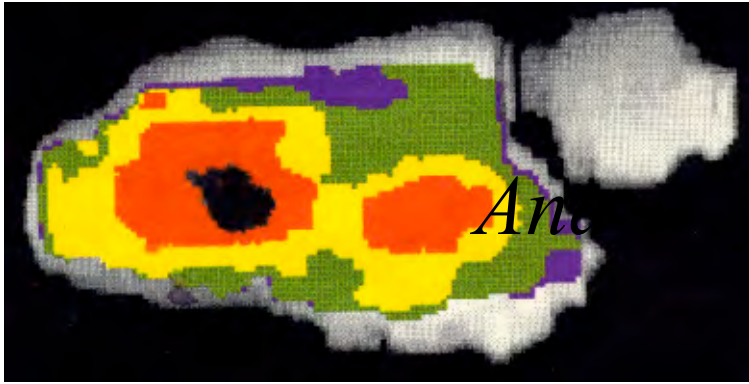
**⇒ *A stable wrist has the ability to return to a definite position after removal of any destabilizing force at any point within the whole physiological range of motion.***



*Analysis and mechanics of the wrist*

- ⇒ *Stability enables optimal joint contact, minimizes stress in any physiological position of the joint.*
- ⇒ *It ensures a smooth and reproducible motion pattern.*
- ⇒ *It warrants optimal load transfer.*





*Anatomy and mechanics of the wrist*

⇒ ***Intact ligaments essential for***

***stability***

smooth

reproducible

correct motion

i.e. perfect load transfer in any

position of the wrist.

## *Anatomy and mechanics of the wrist*

- Ligaments of the proximal carpal row further function.

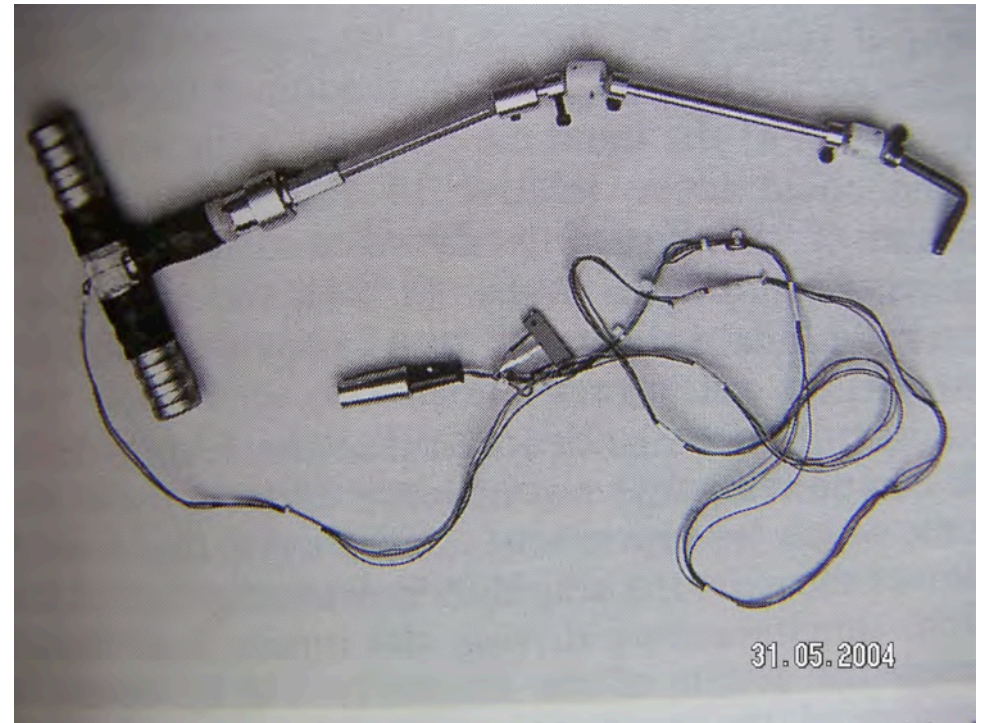
## Mechanics, proximal row

➤ Characteristics of pure torque is important:

pure torque can be introduced with the same effect at any point of the object.

Torque wrench with Hooke's universal joints

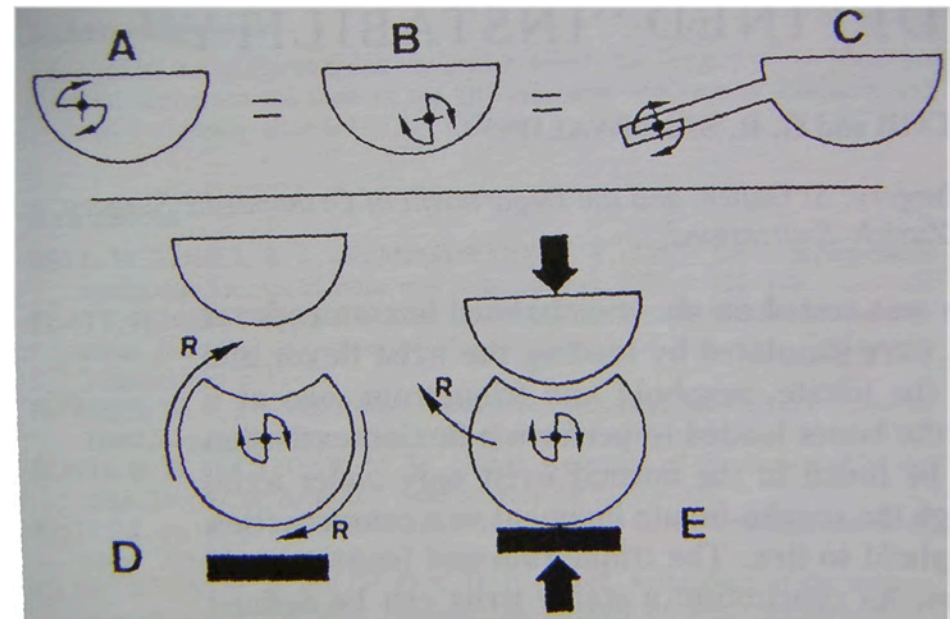
## *The Wrist*



# Mechanics, proximal row

## *The Wrist*

- **Characteristics of pure torque is important:**  
pure torque can be introduced with the same effect at any point of the object.
- **The Reaction R of the pure torque depends on the constraints applied to the object.**



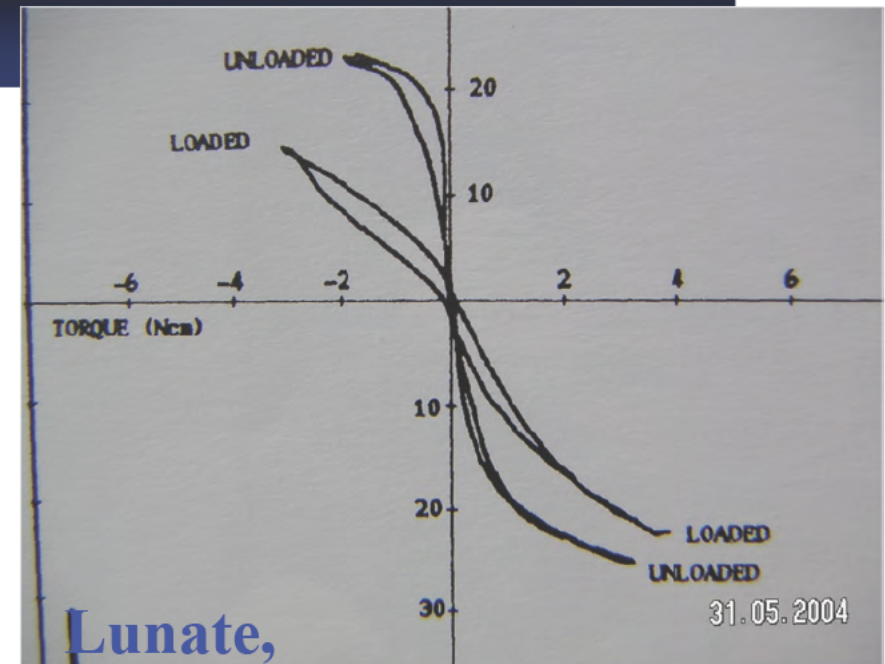
# Mechanics, SL function

## *The Wrist*

- Primary angular motion of the lunate in relation to the applied torque (Ncm).

After *loading*, the shape of the curve became oblique showing that much more torque is required to displace the bones.

*On release of torque, the starting position is immediately regained.*



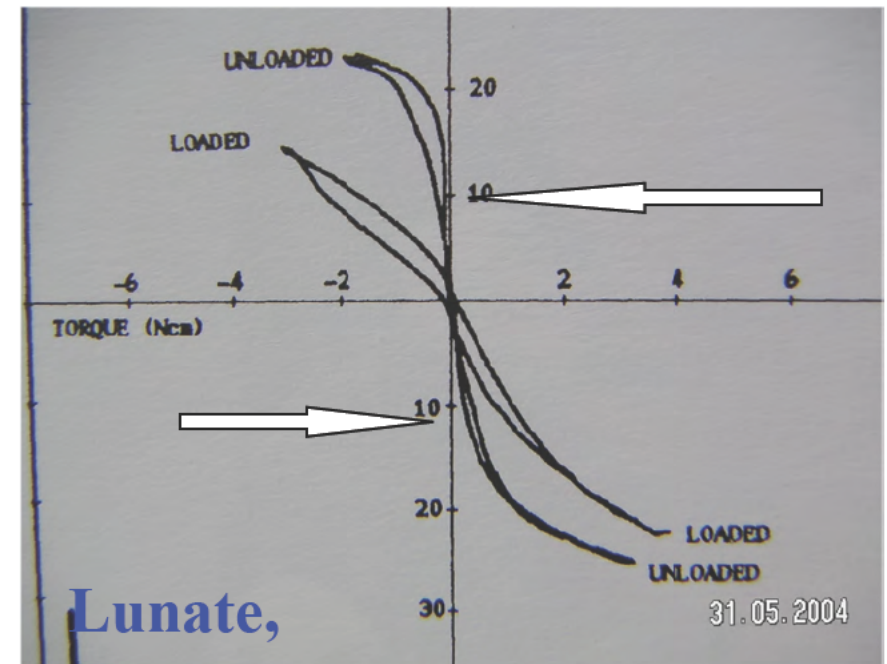
**Lunate,  
flexion**

# Mechanics, proximal row

## *The Wrist*

- Unloaded curve:

Its middle part shows a range of positions within which the bones can be moved on application of a minimum amount of torque, *remaining stationary in the newly acquired position: this represents*



**NEUTRAL EQUILIBRIUM**

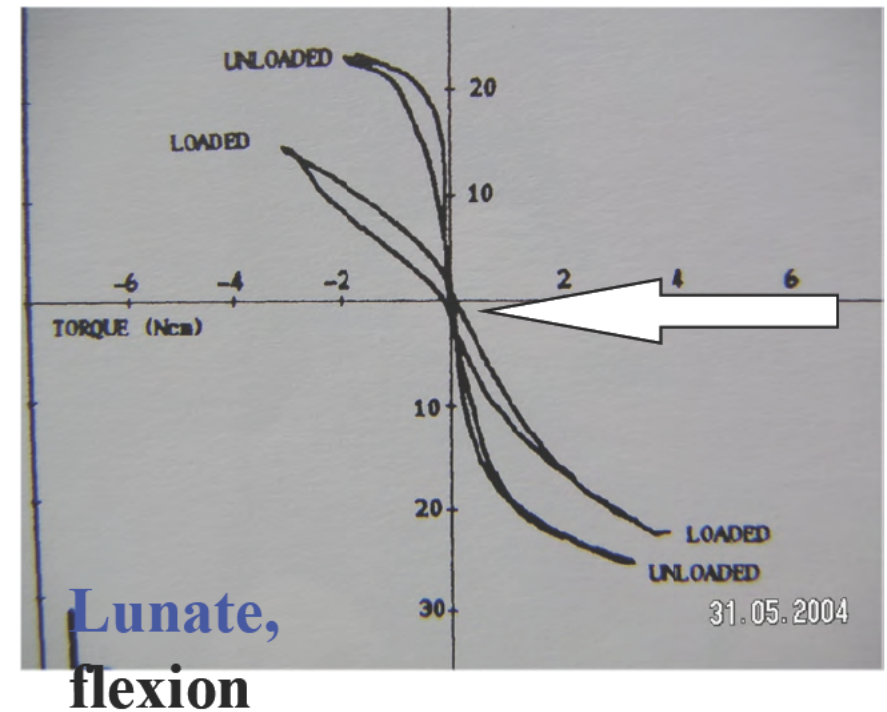
# Mechanics, proximal row

## *The Wrist*

- Loaded curve:

The curves became oblique at the zero-torque crossing. They show that much more torque is required & that the starting position is immediately regained on release of the torque:

*STABLE EQUILIBRIUM*

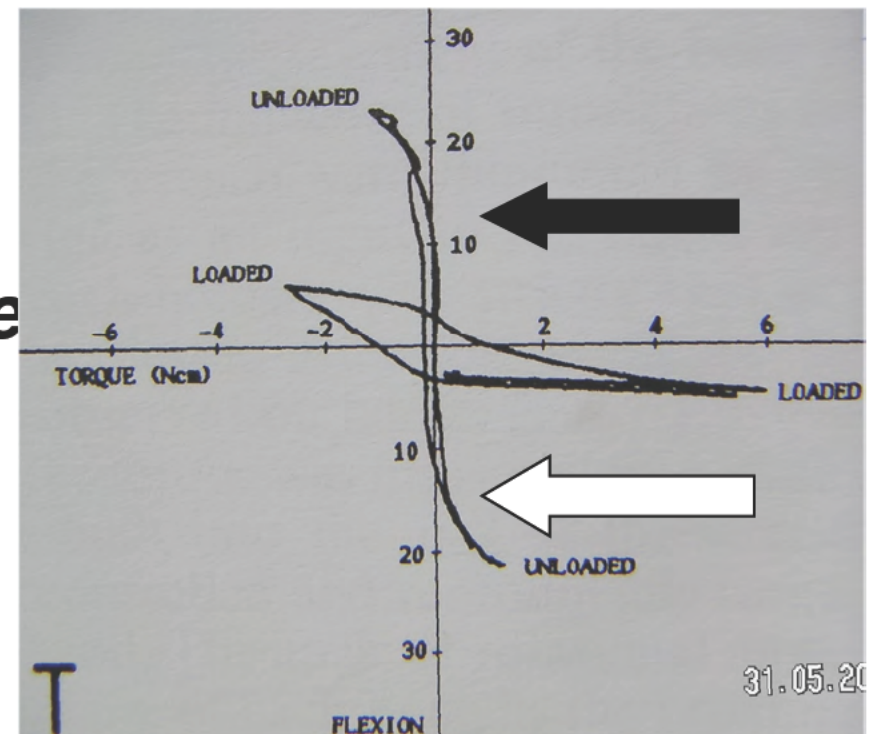


# Mechanics, proximal row

## *The Wrist*

- Primary angular motion of the triquetrum in relation to the applied torque (Ncm).

How much the bone suffers displacement by application of a given small amount of torque *depends on whether the wrist is loaded or not.* The return to the starting position = stable equilibrium





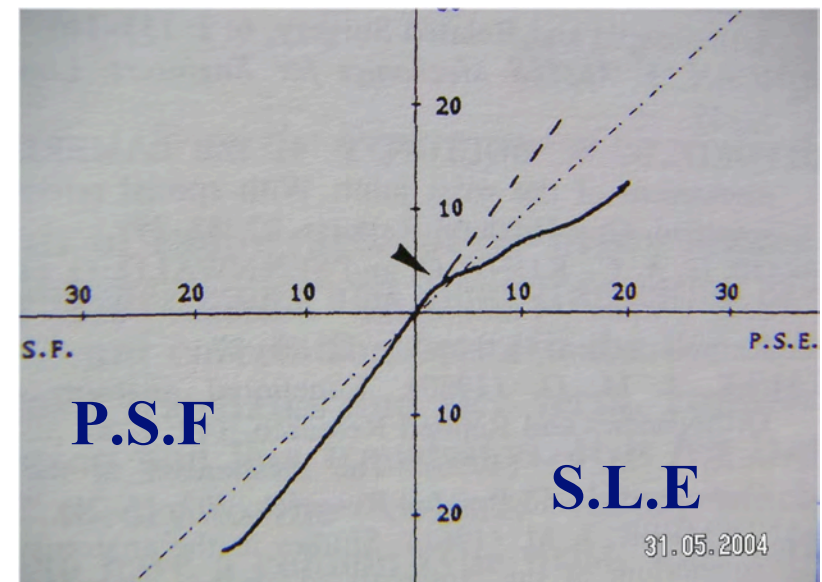
# Mechanics, proximal row

## *The Wrist*

- P.S.F: Primary Scaphoid Flexion.
- S.L.E: Secondary Lunate Extension

**Primary induced motion of the scaphoid causes a secondary motion of the lunate.**

**During extension, the lunate suddenly follows at a slower rate!**



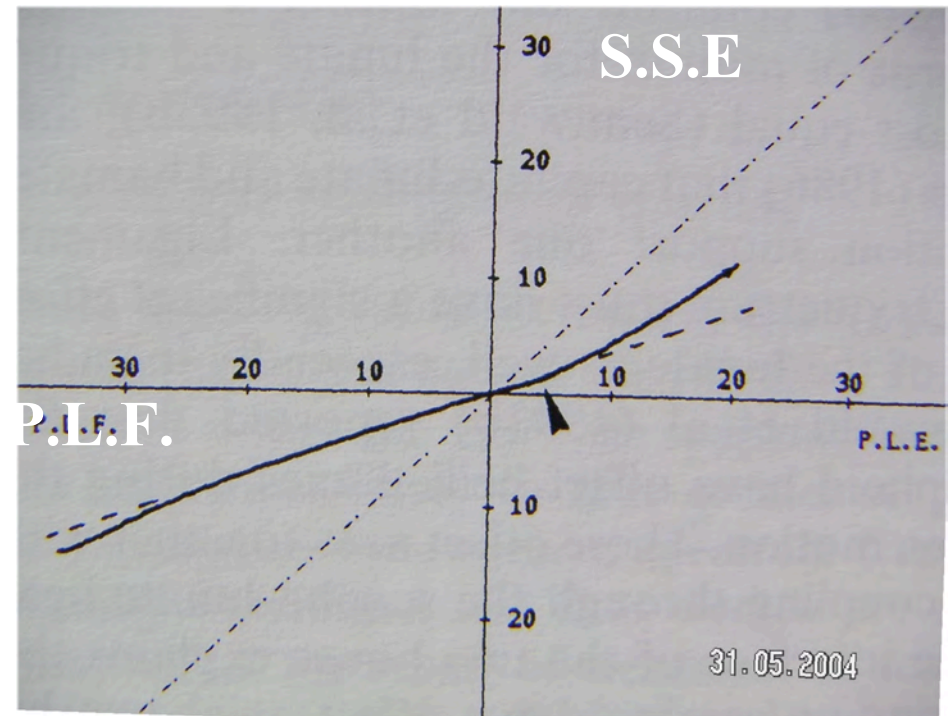
# Mechanics, proximal row

## *The Wrist*

- P.L.F: Primary Lunate Flexion.
- S.S.E: Secondary Scaphoid Extension

**Primary induced motion of the lunate causes a secondary motion of the scaphoid at a lower rate.**

**During Lunate extension the scaphoid suddenly follows the lunate more closely !**



## Mechanics, proximal row

## *The Wrist*

The mechanics shows:

- that motion of the lunate and triquetrum are closely coupled bi-directionally with a lag of about  $5^\circ$ .
- a consistent return to the initial position of the bones of the proximal carpal row.
- that the axial load has a stabilizing effect

## Mechanics, proximal row

## *The Wrist*

- primary motion of each bone in the proximal row induces a secondary motion of the other two.
- coupling between the scaphoid & lunate depends on the direction of primary motion.
- the SL ligament is under tension =  
*tight coupling in flexion,  
uncoupling in extension*

## Mechanics, proximal row

## *The Wrist*

- This might have an adverse effect in the presence of a malunion of the distal radius with dorsal tilting.
- **Permanent tension increases.**
- **the SL ligament is under tension =**  
*tight coupling in flexion,*  
*uncoupling in extension*

## Mechanics, proximal row

## *The Wrist*

- the pattern of motion between triquetrum and lunate are similar.
- capitate-lunate and hamate-triquetrum motion support one another.

## Mechanics, proximal row

## *The Wrist*

### *Stable joint*

*A stable should be defined as one, which, while being loaded **within a physiological range of stress**, does not lose its stable state of equilibrium at any point within the physiological range of motion.*

# *The Wrist*

---

*These findings allow a simplified classification of carpal instability*

*stage 1 without dissociation*

*stage 2a, with dissociation reducible*

*Stage 2 b with dissociation not reducible.*

*stage 3, with carpal collaps.*

*stage 4, with pan - arthrosis.*



**But a problem remains:**

**We now know what is stability,**

**But we still ignore some further  
important aspect of  
Ligament function, and  
forces that might induce pathology.**

*Anatomy and mechanics of the wrist*

# Loads

# *Mechanics and Diagnostic The Wrist*

- **Ligament function**

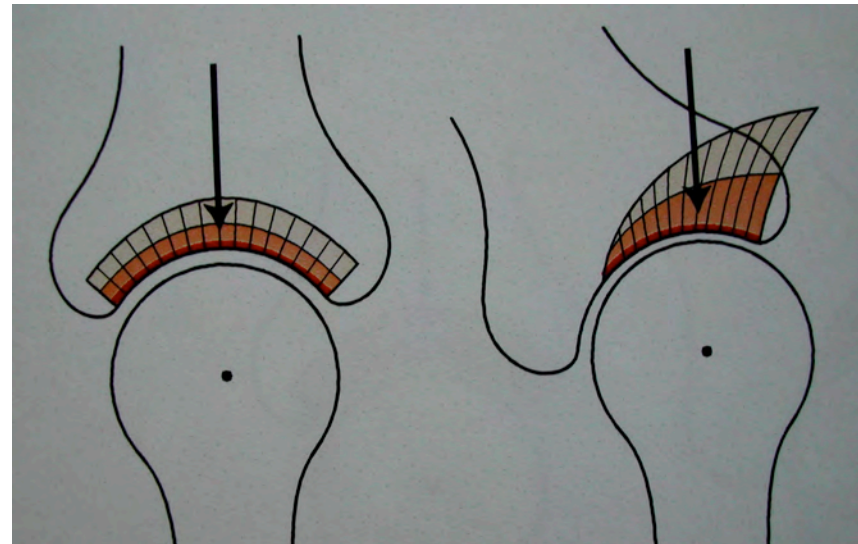
**Not supposed to catch up loads but:**

**Restrain (limit)**

**Adjust (coordinate)**

**Guide (placement)**

**Neutralize (the torque within the first row)**



**The load is transferred through the joint.**

# *Mechanics and Diagnostic The Wrist*

- **Ligament function**

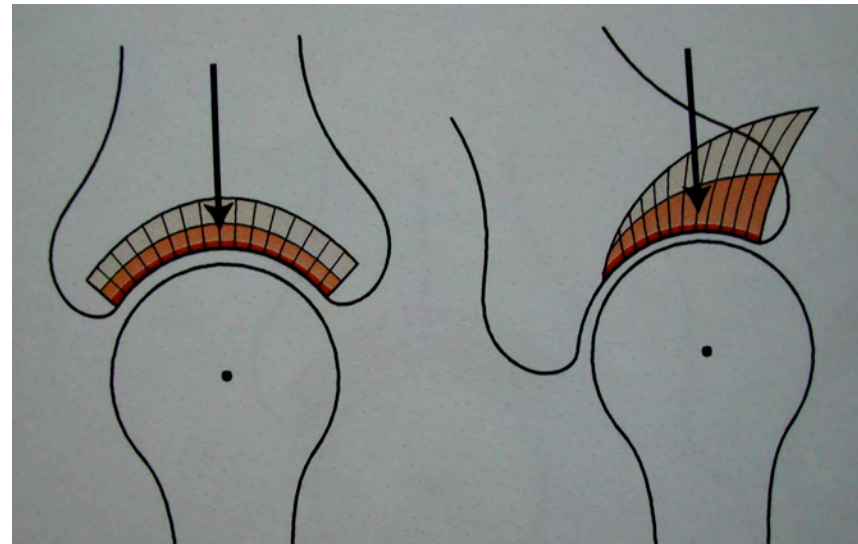
**Not supposed to catch up loads but:**

**Restrain (limit)**

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**Guide (placement)**

**Neutralize (the torque within the first row)**



**If the ligament do not guide correctly the joint, overload can occur locally**

# *Mechanics and Diagnostic The Wrist*

- **Ligament function**

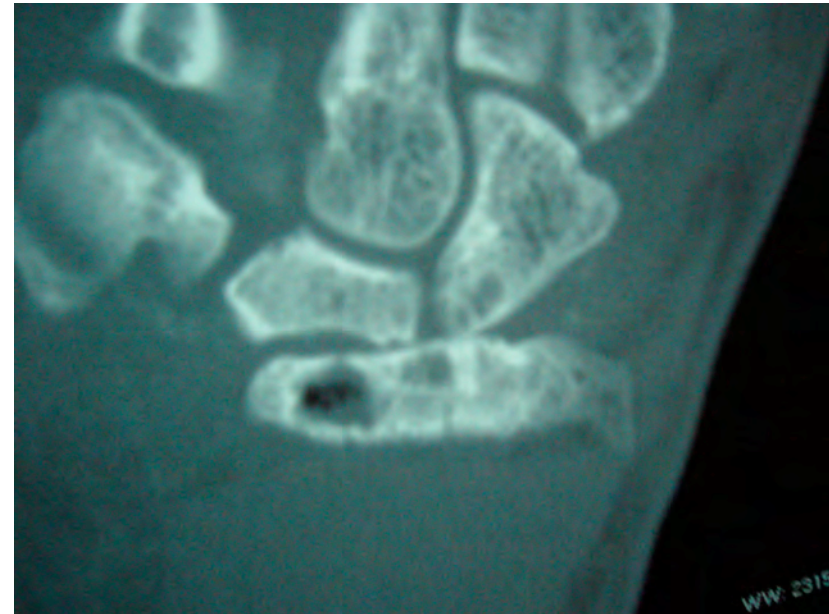
**Not supposed to catch up loads but:**

**Restrain (limit)**

**Adjust (coordinate)**

**Guide (placement)**

**Neutralize (the torque within the first row)**



**If the ligament do not guide correctly the joint, overload can occur locally**

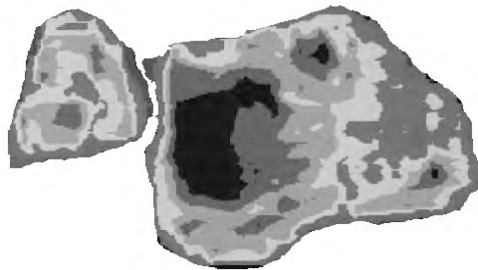
## *Mechanics and Diagnostic*

## *The Wrist*

- Force transmission



S: scaphoid /L:lunate

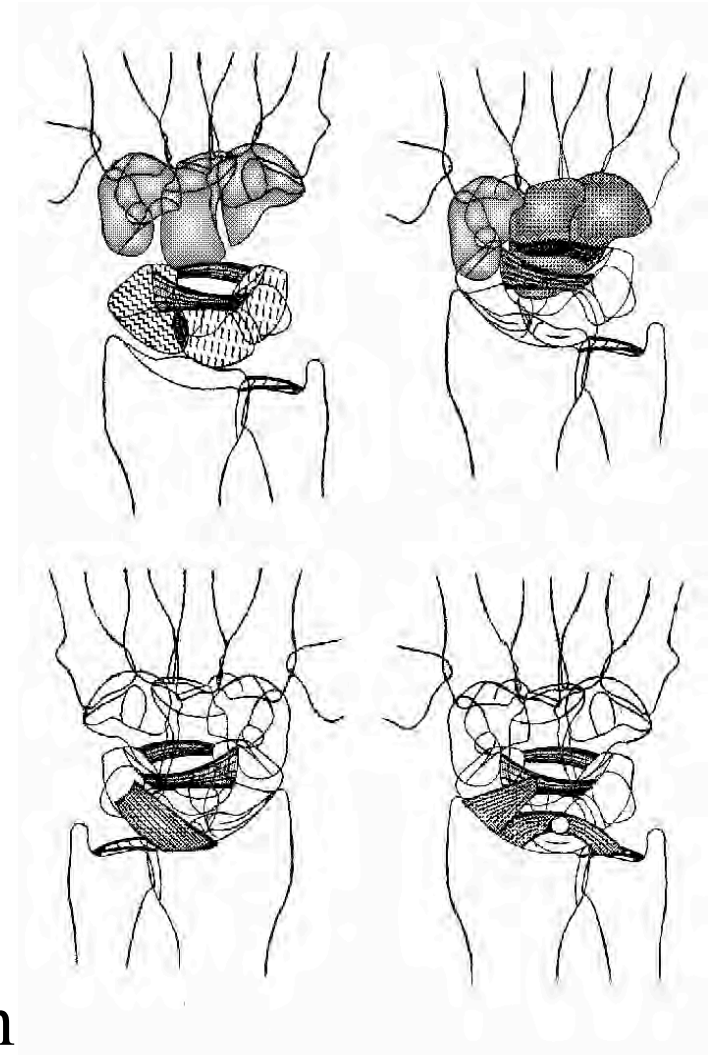


### **First row:**

- a. interactive
- b. suspended
- c. Intercalated
- d. independent

### **Distal row:**

- stable
- Fixed on a moving base
- Loosed fixation



# *Mechanics and Diagnostic The Wrist*

- Problems

Intrinsic

or

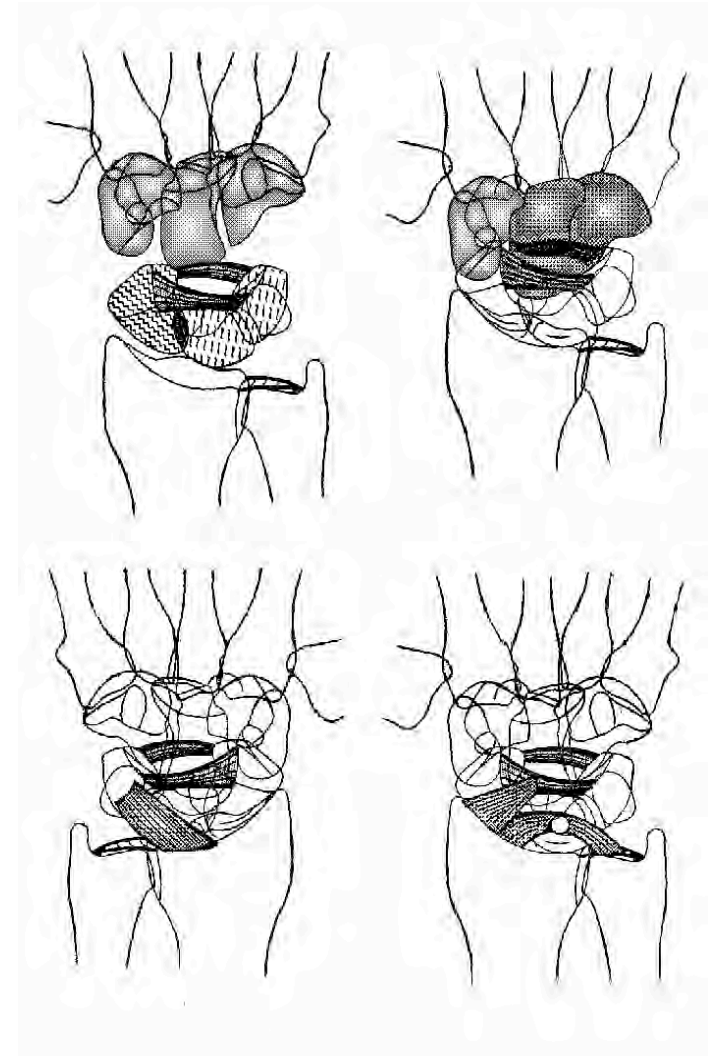
extrinsic

## **First row:**

- a. interactive
- b. suspended
- c. Intercalated
- d. independent

## **Distal row:**

- stable
- Fixed on a moving base



# *Mechanics and Diagnostic The Wrist*

- Problems

Intrinsic

or

Extrinsic

or

combined

DISI,

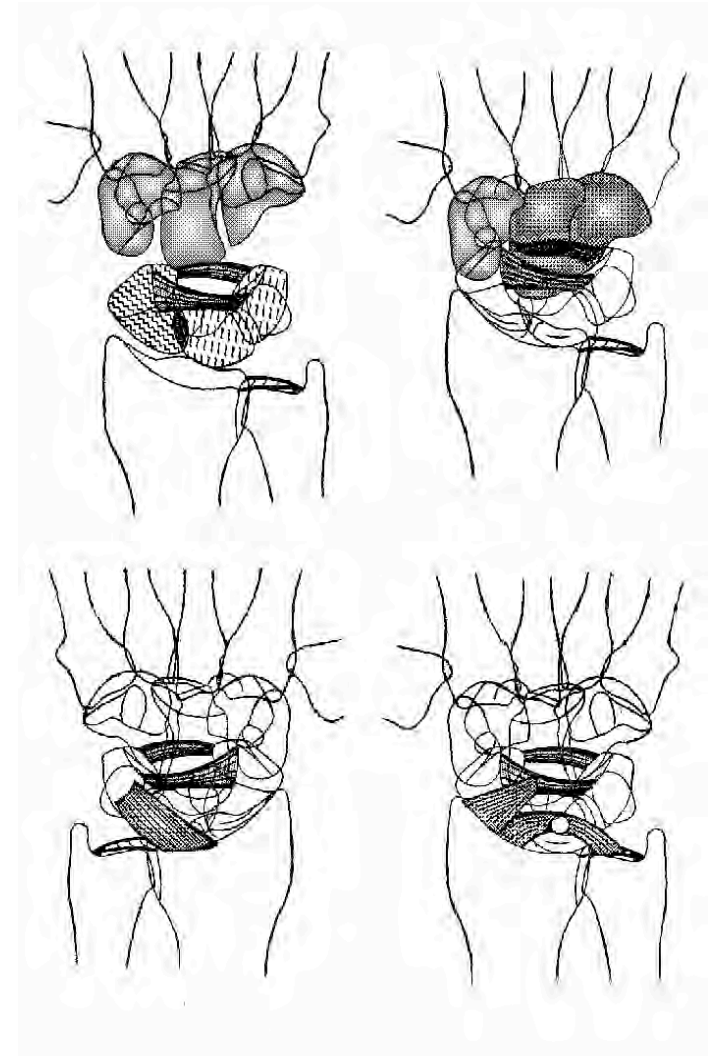
PISI

Dissociation

Translocation

(i.e., Rheuma)

Complex injuries





# *Mechanics and Diagnostic The Wrist*

- Problems

Intrinsic

or

Extrinsic

or

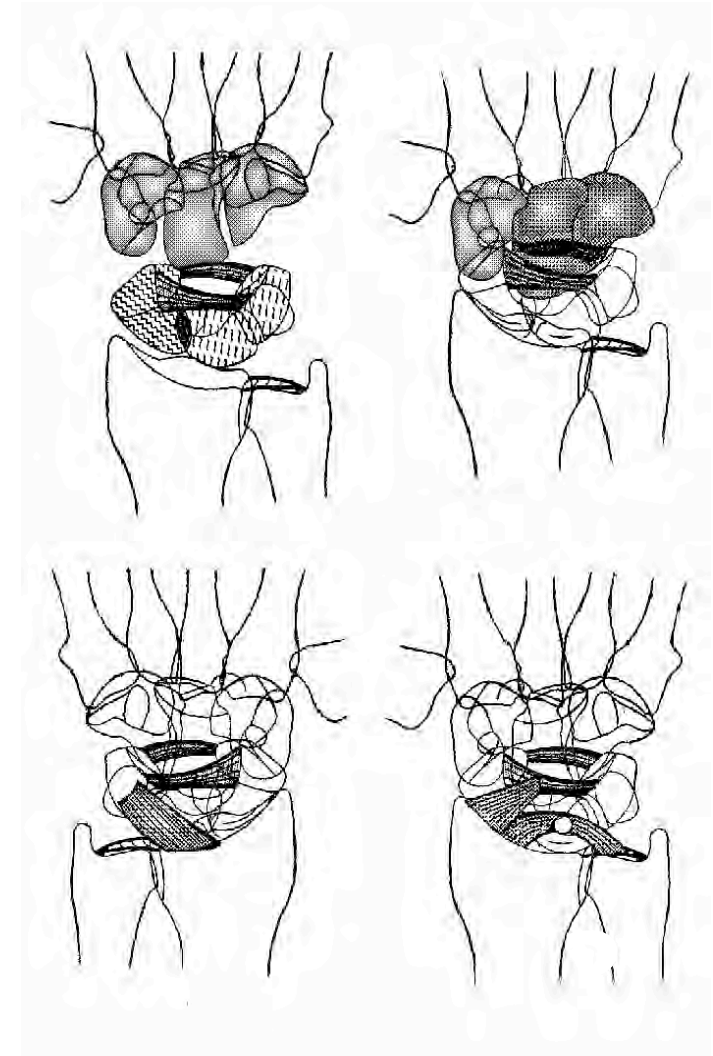
combined

DISI,  
PISI  
Dissociation

Translocation  
(i.e., Rheuma)

Complex injuries

**And which forces are**



- **Basic physical data**

**Force = mass \* acceleration (F=m\*a)**

**where**

**Units of force = units of mass (kg)**

**multiplied by the units of acceleration  
(m/sec<sup>2</sup>), or**

**Weight = Mass \* acceleration = Force**

**Weight = kg \* m / sec<sup>2</sup> = Force (newton)**

**The weight of a men with a mass of 70 kg,  
represents a force of 686 newtons  
( $70 * 9.81 / \text{sec}^2$ )**

**The displacement of this force through a  
distance induces energy, termed “work”  
where**

**Work = force \* distance = Joule**

**If a person falls from 1 meter,**

**We have  $\text{Work} = \text{force} * \text{distance} = \text{Joule}$**

**i.e.**

$$686 * 1 = 686 \text{ Joule.}$$

**If a person falls from 1 meter,**

**We have  $\text{Work} = \text{force} * \text{distance} = \text{Joule}$**

**i.e.**

$$686 * 1 = 686 \text{ Joule.}$$

*If we consider a simple fall, the  
produced energy will vary between  
200 à 700 Joules!*

*Mechanics and Diagnostic*

*The Wrist*

**200 à 700 Joules!**

**This kinetic energy, transmitted through  
the hands and wrist, has to be  
neutralized when the impact occurs!**

*Mechanics and Diagnostic*      *The Wrist*

**200 à 700 Joules to be neutralized.**

**For a cortical long bone submitted to bending,  
plastic deformation appears with 1.18  
joules!**



**Ligament failure (axial loads, best condition)  
vary from 60 to 300 newtons**





**Facit:**

- ❖ Never minimize the potential consequences of an apparent simple fall.
- ❖ Shear stress is extremely important (ligament or bone cannot neutralize them)
- ❖ Combined lesions should be the rule!

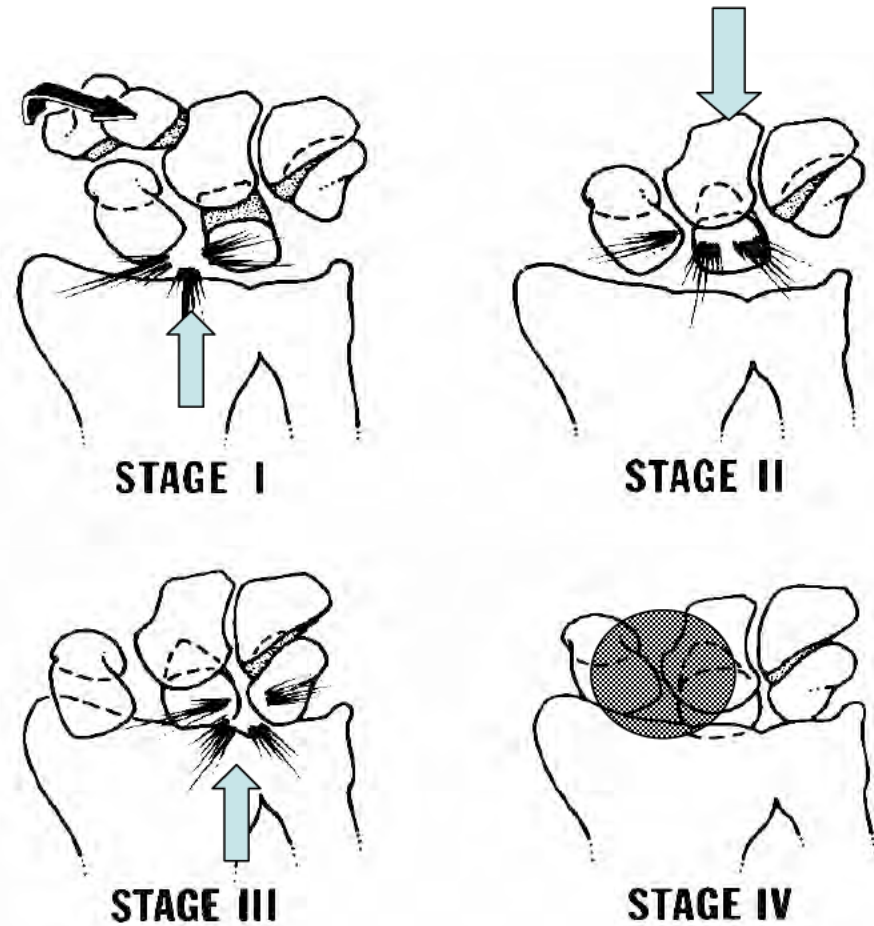
## *Mechanics and Diagnostic*

# *The Wrist*

**Mayfield  
True?**

**Nicolas Barton:**

*I have come to believe  
that standard teaching  
on other aspects is,  
at best, unproved  
and often actually untrue .  
Mechanism of injury?*



*Mechanics and Diagnostic*

*The Wrist*

- To obtain this lesion, you do not need a Kawasaki





# *Mechanics and Diagnostic The Wrist*

- remember

Pain            does not require obvious lesions.

Bone            you need comparative x-rays for  
evaluation (variable anatomy).

Ligament      you may need stress or contrast  
means to appreciate any rupture  
partial or total.

Simple fall    may cause fracture and/or ligament  
ruptures (enough energy).

*Mechanics and Diagnostic The Wrist*

Thank you  
for your  
attention

# The Wrist

---

*Conclusion: mechanics suggest to be simple, for example, for classification of carpal instability*

*stage 1 with dissociation*

*stage 2a, with dissociation reducible*

*Stage 2 b with dissociation not reducible.*

*stage 3 with carpal collapse.*

*stage 4, with pan - arthrosis.*

**Thank you  
for your attention**